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APOGEE

PEAK OF FLIGHT

N E W S L E T T E R

SMARTSim 2.0 is Here!

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Batch Processing with SMARTSim 2.0

Perform thousands of simulations while you sleep

Written by Kenneth J. Karbon

SMARTSim is complementary software to RockSim that solves and optimizes simulation parameters. SMARTSim manages an interface to RockSim and does a lot of grunt work behind the scenes with efficient numerical algorithms. For previous discussion of SMARTSim basics, tips, and examples, see the past Apogee newsletters:

<http://www.apogeerockets.com/education/downloads/Newsletter130.pdf>

<http://www.apogeerockets.com/education/downloads/Newsletter134.pdf>

This article focuses on a new utility in SMARTSim v2.0 that generates many RockSim simulations in batch mode. In computer terms, "batch" means to perform a group of operations without user interaction, usually with a text file of commands. Rather than repeatedly using the RockSim GUI to adjust parameters, run the sims and retrieve the results, SMARTSim can do it for you automatically. This saves time and prevents mistakes when you need to run dozens or even thousands of simulations.

RockSim is a great design tool, and SMARTSim makes it even better. The batch functionality is geared to rocketeers who want to fully understand all the "what-ifs" in their rocket designs. High power, competition, and Team America Rocketry Challenge (TARC) modelers will find it useful when efficiency, precision, and confidence are critical to their work.

How is Batch Processing Different from Regular SMARTSim?

The primary SMARTSim code solves and optimizes pairs of variables. Batch calculations can change many variables and provide reams of data for further analy-

sis. Unlike regular SMARTSim which needs continuous variables (Cd, mass, length, etc.), batch can also accept discrete quantity values, like engines and RockSim "shape codes" for fins and nose cones. The batch utility is perfect to set up all the needed runs in a Design of Experiments (DOE). It can also be used to simulate your list of favorite motors or typical weather conditions at your launch site and save them to the design file. The entire RockSim file is available for study, so the possibilities are endless.

To use batch SMARTSim effectively, users need to have a good understanding of RockSim, the "rkt" design file conventions, and computer spreadsheets. Batch processing is a 3-step method in SMARTSim v2.0:

1. Create a batch file in SMARTSim.
2. Fill in a run "matrix" with combinations of parameters at the end of the file.
3. Return to SMARTSim and execute the completed batch file.

The process will be explained in more detail as we work through some examples that illustrate the wide range of applications that SMARTSim offers.

Example 1 - Fin Study

This simple, step-by-step example will demonstrate how to use the SMARTSim batch utility. Our goal is to determine the effects of fin number (3 or 4), shape (elliptical or trapezoidal), and span (1 inch or 2 inch) on maximum altitude for a given rocket design. The three fin parameters will be evaluated at 2 levels each for a full factorial of 8 combinations (Remember that $2^3 = 8$). These 8 combinations are just one way of defining the "design space" for study. There are many different tools and methods to set up experiments and analyze designs. DOE is a field of engineering all to itself and beyond the scope of this article.

First, I prepared a RockSim design as usual and created at least one simulation with the desired flight events and weather conditions. Open this file in SMARTSim. From the top menu, choose Tools>Create Batch File. This opens a new form with a tree view browser of the rocket file as in Figure 1. Navigate to the part Fin Set in the tree (The search function is handy here). Select Fin Count, Shape Code, and Semi-span and "Add" them as "Control Factors." These are the three fin parameters whose values we "control" in our study. Next, find Max

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Apogee Components, Inc. is pleased to announce the first in a yearly grant program geared toward model rocketry education organizations!

The rules are simple:

1. Entrants must submit an essay to Apogee. There is no length requirement for the essay.
2. Any club, organization, school program, etc. is eligible for entry. This would include rocketry clubs or prefectures, 4H, scouts, etc.
3. The content and purpose of the essay is as follows:
 - If we gave you \$300.00, How would you use it to impact the rocketry community?
 - How many people you think it will reach?
 - How many people are involved in the organizing and running of the event?

- How big of an effect will it have on the rocketry community?

4. One of the biggest things to keep in mind when composing your essay is, "How is what I am planning unique"?

There will be only one winner and recipient of the grant, which is \$300.00 toward any order with Apogee Components.

The deadline for entry is November 30, 2006.

The grant winner will be announced on January 1, 2007.

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Altitude in the first Simulation Results (number 0) and add it as an "Output Factor." "Write" the batch file.

Open the batch file (comma-delimited csv format) in a spreadsheet like Excel (Figure 2). Any text processor will also work, but spreadsheet functions make it easy to copy, paste, and fill the run matrix. The first 5 lines contain info to help SMARTSim perform the batch process. Lines 6 thru 8 indicate the control and output factors, your preferred units, and their names in the RockSim design file. Do not modify lines 1-8.

Starting with line 9, I filled in the values for the 8 combinations of fin parameters. Each row represents a new simulation to run in batch with SMARTSim automatically updating the values of the factors. Note that Shape Code = 0 refers to trapezoidal and Shape Code = 1 refers to elliptical. (Go to Help > RockSim File XML Elements for definitions.) Do not put anything in the Max Altitude output column because SMARTSim will retrieve this data for us at the end of each sim. Save the csv file and close.

Filling the run matrix is performed outside of SMARTSim to allow for the most flexibility. The user can apply any DOE method he chooses. Entering repeated run combinations with a spreadsheet is far easier than typing values into some sort of GUI or text editor. Note that the first 8 lines in the file are unique to this particular RockSim design file and must be re-created for different rkt files, simulations, or factors. However, the run matrix starting in line 9 can be re-used and pasted into other batch files. This feature will be evident in the next example.

Go to Tools > Run Batch Simulations (Figure 3).



Figure 1. Selecting Batch Parameters for the Fin Study

Control	Control	Control	Control	Output
Fin Count	Shape Code	Span	Max Altitude	
3	0	3	2.0	
3	0	3	1.0	
3	1	3	1.0	
3	1	3	2.0	
4	0	3	2.0	
4	0	3	1.0	
4	1	3	2.0	
4	1	3	1.0	

Figure 2. Fin Study Batch File in a Spreadsheet

Browse for the batch file that was just created and edited. Select the output options. New simulations can be appended to a RockSim file or output values written back to the batch text file. For this example, check the box to "Add results to output columns of batch file." Click Run. A status window will appear detailing the progress of the 8 new simulations.



Figure 3. Batch Run Form

When complete, open the batch file again as in Figure 4. The results for Max Altitude for each run are added to the appropriate column. The second combination (3 fins, trapezoidal, 1 inch span) gives the highest altitude (2533 ft) in the simulation.

Fin Count	Shape Code	Span	Max Altitude
3	0	3	2121.212
3	0	3	2533.515
3	1	3	2112.200
3	1	3	2380.400
4	0	3	2163.11
4	0	3	2412.002
4	1	3	2181.900
4	1	3	2181.900

Figure 4. Batch File with Output Results

Example 2 - Create a List of Engine Simulations Appended to a RockSim File

Instead of 3 variables, say you had 6, each at 3 levels. That's a full factorial of 729 (36) combinations. It would take you days to perform the study by manually adjusting the parameters and pressing the "launch" button in the RockSim GUI. Only with batch processing can you attempt such a large number of simulations. The need for a spreadsheet is also obvious when setting up and analyzing a batch file of this magnitude. To further test the robustness of the software, I submitted a batch file with six factors and 10,000 simulations! The job ran for several hours overnight, but no memory or overflow errors occurred.

Example 2 - Create a List of Engine Simulations Appended to a RockSim File

I use the same group of 29mm and 38mm motors in all my HPR rockets. For each new RockSim design file that I create, I want to simulate the same set of motors (about 20 of them). This requires selecting the engine and delay combinations over and over again 20 times in the RockSim GUI. I don't like this kind of donkey work, so this application in particular inspired me to develop the batch processor in SMARTSim.

The next example runs simulations for every 18mm

continued on page 5

engine in the RockSim database and appends them to a RockSim file. The list of engines can be saved and used in batch for new design files created in the future.



Figure 5. Batch Create Form with Engine Control Factors

Engine Code, and Engine Delay must be selected as control factors. I also added Simulation Name as a con-

Also, if you receive a rkt file from another modeler (through the EMRR database for example), you can readily append your favorite motor combinations to it.

Open a rkt file in SMARTSim and launch the Batch Create form (Figure 5). The motor types are found in the Engine Set of the Simulation Results. To fully specify a motor, Engine Mfg,

trol factor because this element describes the loaded engines in the RockSim GUI display. No output factors are needed in the batch file because we are going to append the new simulations to a RockSim design file.

Open the batch file in a spreadsheet and add lines for each motor specification as shown in Figure 6. Names for the manufacturer and engine code must follow the RockSim database format. A total of 16 motors of 18mm diameter are in my database, representing Aerotech, Estes, and Quest. Use an Engine Delay of -1, as this indicates to RockSim to calculate "all" delays. Simulation Name is how RockSim displays the loaded engine. I ba-

Engine Code	Engine Delay	Simulation Name
Aerotech E12	-1	Aerotech E12
Aerotech E20	-1	Aerotech E20
Aerotech E30	-1	Aerotech E30
Aerotech E40	-1	Aerotech E40
Aerotech E50	-1	Aerotech E50
Aerotech E60	-1	Aerotech E60
Aerotech E70	-1	Aerotech E70
Aerotech E80	-1	Aerotech E80
Aerotech E90	-1	Aerotech E90
Aerotech E100	-1	Aerotech E100
Aerotech E110	-1	Aerotech E110
Aerotech E120	-1	Aerotech E120
Aerotech E130	-1	Aerotech E130
Aerotech E140	-1	Aerotech E140
Aerotech E150	-1	Aerotech E150
Aerotech E160	-1	Aerotech E160
Aerotech E170	-1	Aerotech E170
Aerotech E180	-1	Aerotech E180
Aerotech E190	-1	Aerotech E190
Aerotech E200	-1	Aerotech E200
Aerotech E210	-1	Aerotech E210
Aerotech E220	-1	Aerotech E220
Aerotech E230	-1	Aerotech E230
Aerotech E240	-1	Aerotech E240
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Aerotech E290	-1	Aerotech E290
Aerotech E300	-1	Aerotech E300
Aerotech E310	-1	Aerotech E310
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Aerotech E360	-1	Aerotech E360
Aerotech E370	-1	Aerotech E370
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Aerotech E2990	-1	Aerotech E2990
Aerotech E3000	-1	Aerotech E3000
Aerotech E3010	-1	Aerotech E3010
Aerotech E3020	-1	Aerotech E3020
Aerotech E3030	-1	Aerotech E3030
Aerotech E3040	-1	Aerotech E3040
Aerotech E3050	-1	Aerotech E3050
Aerotech E3060	-1	Aerotech E3060
Aerotech E3070	-1	Aerotech E3070
Aerotech E3080	-1	Aerotech E3080
Aerotech E3090	-1	Aerotech E3090
Aerotech E3100	-1	Aerotech E3100
Aerotech E3110	-1	Aerotech E3110
Aerotech E3120	-1	Aerotech E3120
Aerotech E3130	-1	Aerotech E3130
Aerotech E3140	-1	Aerotech E3140
Aerotech E3150	-1	Aerotech E3150
Aerotech E3160	-1	Aerotech E3160
Aerotech E3170	-1	Aerotech E3170
Aerotech E3180	-1	Aerotech E3180
Aerotech E3190	-1	Aerotech E3190
Aerotech E3200	-1	Aerotech E3200
Aerotech E3210	-1	Aerotech E3210
Aerotech E3220	-1	Aerotech E3220
Aerotech E3230	-1	Aerotech E3230
Aerotech E3240	-1	Aerotech E3240
Aerotech E3250	-1	Aerotech E3250
Aerotech E3260	-1	Aerotech E3260
Aerotech E3270	-1	Aerotech E3270
Aerotech E3280	-1	Aerotech E3280
Aerotech E3290	-1	Aerotech E3290
Aerotech E3300	-1	Aerotech E3300
Aerotech E3310	-1	Aerotech E3310
Aerotech E3320	-1	Aerotech E3320
Aerotech E3330	-1	Aerotech E3330
Aerotech E3340	-1	Aerotech E3340
Aerotech E3350	-1	Aerotech E3350
Aerotech E3360	-1	Aerotech E3360

continued from page 5

sically followed this format, but you can use any descriptive text in this field.

Goto Tools
> Run Batch Simulations (Refer to Figure 3). Select "Append simulations to RockSim file" as the output option and give a file name. Be careful when appending many simulations as this creates very big rkt files. Press Run. When complete, read the appended rkt file into RockSim and see the 16 new simulations (Figure 7). Save the batch file in a handy location and paste the motor combinations into batch files for new designs.

A similar application would be to define weather/starting conditions that are "typical" of your launch site. Control factors could be engine, wind, and launch angle, with output factors of optimal delay and landing

Simulation	Motor	Altitude	Velocity	Time	Delay	Angle	Wind	Temp	Pressure	Humidity	Altitude	Velocity	Time	Delay	Angle	Wind	Temp	Pressure	Humidity
1	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
2	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
3	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
4	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
5	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
6	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
7	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
8	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
9	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
10	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
11	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
12	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
13	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
14	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
15	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0
16	A10	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0	1000	100	1.0	0.0	0.0	0.0	0.0	0.0	0.0

Figure 7. Appended Simulations (1 to 16) in RockSim

range. From the batch output file, make lookup tables and graphs that you can use in the field.

Summary

Consider the famous quote of mathematician and computer scientist Richard Hamming (1915-1998):

"The purpose of computing is insight, not numbers."

Batch processing captures the essence of this motto very nicely. SMARTSim crunches the numbers while you focus on your rocket design. If you want to fully explore all the "what-ifs" or just want to save time with your RockSim simulations, then you need SMARTSim.

In a Part 2 of this article, I will show how batch simulations with SMARTSim along with powerful data processing can help you win the TARC 2007 competition.

About the Author

Ken Karbon is a rocketeer from Michigan and the developer of SMARTSim. He holds a Masters Degree in Mechanical Engineering and works as an aerodynamicist in the auto industry, specializing in CFD simulation. For more information email smartsim@comcast.net

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TIP OF THE FIN

Many commercial kits come with an elastic shock cord. As is said very often, "The only place elastic belongs is in your underwear". It is highly recommended to replace the elastic shock cord with tubular nylon or tubular Kevlar. A rule of thumb is to use 3 times the the length of the rocket.



All of our Apogee and Dynastar kits come standard with Kevlar®. Kevlar® is fire-proof, stronger than steel, and is used to make bullet-proof vests. Your shock cords will easily last the life of the rocket. Our cords are braided and uncoated of waxes

or sealers (so you can glue it).

You can find this product at http://www.apogeerockets.com/construction_supplies.asp#shock_cord.

QUESTION AND ANSWER CORNER

Davin Lim asks, "I've run into an odd situation regarding how Rocksim computes drag on nose cones. As I reduce the length of a 2.5" diameter elliptical nose cone from 5 inches to 2.5 inches, the calculated drag goes down (and corresponding altitude prediction goes up). I'm guessing I'm entering a region where the drag equations break down (or maybe this is just a bug?). Do you happen to know at what point (e.g. length v. diameter) that the drag computations aren't reliable anymore?"

The DATCOM equations that RockSim uses for the nose cone drag are based on the wetted surface area of the part. The smaller the part, the lower the drag. You'll also find cone shape has less drag than others because cones have smaller surface areas. It is not perfect to real-world conditions, but it will get you in the ballpark for most rockets.

- Tim van Milligan (a.k.a. - "Mr. Rocket")

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Mike Payne	Level 2	CO
Bob Dixon	Level 1	CO
Chris Frazier	Level 2	CO
Ken Plattner	Level 2	CO
Ken Reilly	Level 2	CO
Steve Frazier	Level 2	CO
Stephen DeShong	Level 1	FL
Bobby Wright	Level 1 & 2	CA
J C Worhen	Level 1 & 2	ID
Ken Hogren	Level 2	IL
Kurt Savegnago	Level 2	IL
Paul Kent	Level 2	MA
Kelsey Young	Level 1	MN
July - Craig Nelson	Level 2	MN
Lawrence Southwick, Jr.	Level 2	NV
Steve Hedland	Level 3	NV
Rollin Bateman	Level 1	NY
Chris Hyers	Level 2	MO
David Lucas	Level 2	MO
Steve Gerber	Level 3	OH
David Tietz	Level 2	OH
Greg Cornett	Level 2	OH
Thomas P. Secrist	Level 2	OH
Ted Hipple	Level 1	OH
Patrick Chiles	Level 1	OH
Larry B. Rice	Level 1	OH
Robert Krausert	Level 1	OR
Tom Aument	Level 2	PA
Bob Moreash	Level 3	TX
Buzz Hempel	Level 2	TX
Rick Hill	Level 2	VA
Alan R. Buettner	Level 1	WA

Featured Certifier

Jim Jarvis achieved his L3 certification in grand style at LDRS 25. On the Saturday of the launch, in the morning high altitude window he successfully completed the most extreme certification flight in history. Flying his completely hand built rocket, all carbon fiber laid up by his own hand, he flew an Animal Motor Works N4000



Jim Jarvis, Level 3

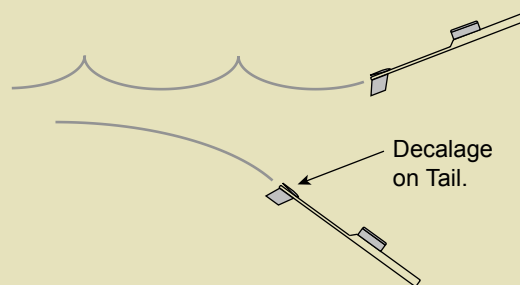
to approximately 35,000 feet and mach 2.8 plus. . I think that the most extreme cert flight prior to this one was the L3 of Dan Stroud at LDRS 21. Not only did Jim have the most extreme cert flight on record, he also set the altitude record for N motors (not updated yet on the TRA website). Jim is a proud resident of Austin, Texas and a member in good standing with the Austin Area Rocketry Group.

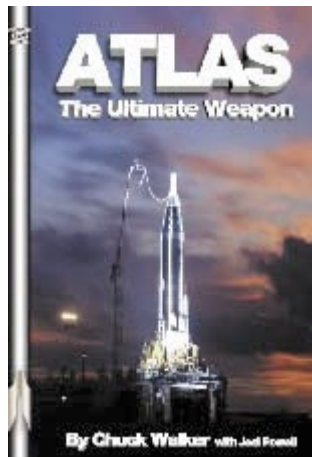
Correction: Please note In newsletter # 166, Layne Sunderlin was listed as certifying Level 2. He only certified to Level 1.

If you have a rocketry related accomplishment, whether it is with a club, 4H, school, please email me at johnm@apogeerockets.com so we can recognize your achievement!

DEFINING MOMENTS

Decalage is a downward angle-of-attack of the tailfins (compared to the angle-of-attack of the main wings) on a glider. The purpose of decalage is to allow a glider to pull out of a dive.





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WEB SITES WORTH VISITING

The website for this issue is for all you high power certifying enthusiasts! "RocketDreemz" is found at http://www.rocketdreemz.com/rocket_dreemz_001.htm. It is owned by Jim Ballard and is a great site to learn about certifying at all three levels. Most of the emphasis is on his Level 3 project, but information on the beginning of his certification journey is also posted.

In 2003 Jim says, "I discovered there were much bigger and more powerful facets

of the hobby that I had no idea existed. I began surfing the net and was amazed at what I found. Well, needless to say... I WAS HOOKED! Just ask my wife..." Jim's L-1 flight was on an H128 that took his rocket to about 1200 feet. Next came time for a Level 2 project. For

this, he chose a 4" diameter missile in which he delved into dual-deployment. After passing his Level 2 written test, Jim slapped a CTI J330 in and the rocket hit 3661 feet.

The main thrust of the site, of course, is Jim's Level 3 project which got him his certification at LDRS '06! With an 8" diameter beast and all scratch-built, Jim really shows off his skills as a modeler as he takes you through many pages of

details on the construction of this rocket. He put the 60 pound monster up on an M1550 to certify.

Also helpful is a page that Jim dedicates to "tools of the trade", which goes through the devices he uses to create his designs. This is a great site to peruse when preparing for your own certifications. Jim's details will get your creative juices flowing and help you think through a lot of the details that are involved with certifying high power at any level!

